Introduction to System Identification for Neural Systems

> Lecture I: Modeling & Identifying Neurosystems

# Systems I Have Studied



### Human

- Standing balance / posture control
- Running



- Weakly Electric Fish
  - Midbrain neurons

# What if you wanted a model of a human flying



#### Like balance, flying is a sensorimotor stabilization task.

# Modeling Approach



Use a flight simulator with an autopilot that mimics the brain of a real pilot.

# Model Complexity Varies







### Most autopilots ... trivialize human controller

Autopilot behaving human ... trivializes variability in pilot population







Good model

For each pilot, System ID tells you the states of knobs and switches.

# Need #1: Simple Behavior



Yes!





No!







# "Need" #2: Input

## Balance: Move platform & visual surround

### Flight: Change the wind





# Need #3: Data





#### Balance:





### Flight:

# Need #4: Parameterized Model

### Flight:

**Balance**:















# Need #5: Statistics of Noise

Noise is any input you do not know.







### Needs

- I. Simple Behavior to Be Studied
- 2. Known Inputs to System During Behavior
- 3. Data Collected During Behavior
- 4. Parameterized Model of System ...
- 5. Including Statistics of Noise (Unknown inputs)

System Identification: Infers the Values of Parameters (Knobs & Switches) and/or Decides If the Model Fits the Data

# System ID Terminology

- Infer Position of Knobs: Parameter Estimation
- Infer Position of Switches: Model Selection
- Decide if Model Fits Data: Model Validation

### Parameter Estimation

K+ Maximal Conductance mS/cm^2



Objective Function Quantifying How Well Model Fits Data (As Two Knobs Vary)

### **Optimization:** Find Max



# Hidden Variables Confound Likelihood Computation



Solution: Bayesian Filtering

# Diagnosis of Balance Deficits



#### Important problem impacting many lives

# What Can Go Wrong With Balance?





#### Patient populations are heterogeneous!

### Want Clinical Data



Useful for designing interventions and monitoring progress

# Enter Weakly Electric Fish



# Tracking: Like Balance, Sensorimotor Stabilization



# Prey Capture:



Courtesy Malcolm Maclver Northwestern University

# Jamming Avoidance

